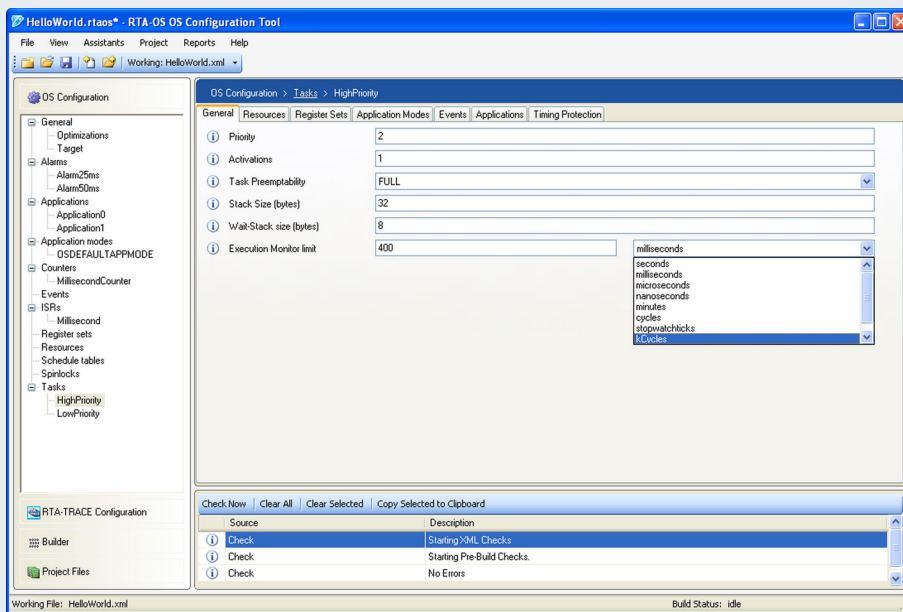


# RTA-OS

## Cypress Traveo-II with the Green Hills Compiler



### Features at a Glance

AUTOSAR R4.3 compliant  
Multicore OS

Supports all scalability  
classes

MISRA-C:2012 compliant

RTOS overhead:  
69 bytes RAM  
0 bytes ROM

Category 2 ISR latency:  
82 CPU cycles

### RTA-OS

RTA-OS is the new generation operating system from ETAS that conforms to the AUTOSAR OS specification and builds on the benefits of the successful RTA-OSEK product. It provides a toolsuite that includes a PC-based graphical configuration tool and adaptive OS generation capabilities to deliver flexible, fast solutions for a wide range of automotive microcontrollers.

The graphical configuration tool allows all OS objects to be configured, and creates AUTOSAR conformant XML files describing the OS configuration. In addition, it provides automatic verification against the AUTOSAR XML schema and allows users to create projects for easy management of multiple files.

RTA-OS improves on RTA-OSEK in several areas, including better runtime performance and smaller memory footprint,

support for multiple processor environments, and automatic support for up to 1024 tasks. The powerful performance analysis tools developed for RTA-OSEK have been updated for RTA-OS to allow hard real-time requirements to be met.

### RTA Product Family

RTA-OS integrates seamlessly with other tools in the RTA product family, including:

- RTA-RTE – a mature, robust production quality AUTOSAR RTE Generator.
- RTA-TRACE – a software logic analyser that allows the runtime behaviour of RTA-OS to be observed.

### Microcontroller Support

RTA-OS supports all variants of the Cypress Traveo-II family of microcontrollers.

## Compiler Toolchain

RTA-OS for the Cypress Traveo-II has been developed with the Green Hills v2017.1.4 compiler.

Due to the adaptive code generation of RTA-OS, it is possible to use other versions of this compiler to build applications.

## ORTI Debugger Support

RTA-OS can generate OSEK Runtime Interface information for the Lauterbach debugger.

## Interrupt Model

RTA-OS supports up to 10 interrupt priority levels on the Traveo-II

## Memory Model

RTA-OS supports the standard 32-bit EABI memory model provided by the Green Hills compiler.

## Maximum Number of OS Objects Allowed by RTA-OS

	BCC1	BCC2	ECC1	ECC2
Max. no. of tasks	Up to 1024			
Max. tasks per priority	Up to 1024			
Max. queued activations	1	$2^{32}-1$	1	$2^{32}-1$
Max. events per task	n/a	n/a	32	32
Max. alarms	$2^{32}-1$			
Max. software counters	$2^{32}-1$			
Max. hardware counters	$2^{32}-1$			
Max. nested resources	$2^{32}-1$			
Max. standard resources	$2^{32}-1$			
Max. internal resources	Not limited by RTA-OS			
Max. application modes	$2^{32}-1$			
Max. schedule tables	$2^{32}-1$			
Max. expiry points per schedule table	$2^{32}-1$			

## Memory Overhead of RTA-OS

Memory Type	Overhead (bytes)
RAM	69
ROM/Flash	0

In addition to the OS overhead, each object used by an application has the following memory requirements:

Object	RAM (bytes)	ROM (bytes)
Task	0	20
Category 2 ISR	0	8
Resource	4	8
Alarm	12	2
Counter	4	20
Schedule Table	12	13
Expiry Point	0	4

## Performance

The following table gives the key RTA-OS kernel performance data measured in CPU cycles. All measurements were taken on a TVII\_B\_E\_1M with a 160MHz clock speed.

Task Type	Execution Time	Ref.
Pre-emption	90	A
Normal Termination	50	B
Task Switch	56	C
ChainTask	115	D
WaitEvent	237	E
SetEvent	305	F
Schedule	80	G
ReleaseResource	76	H
Category 2 ISR Entry Latency	82	I
Category 2 ISR Exit Latency resuming interrupted task	71	J
Category 2 ISR Exit Latency with task switch	156	K
Category 1 ISR Latency	42	L

The following figures illustrate how the RTA-OS kernel overheads are allocated during the operations given in the above table:

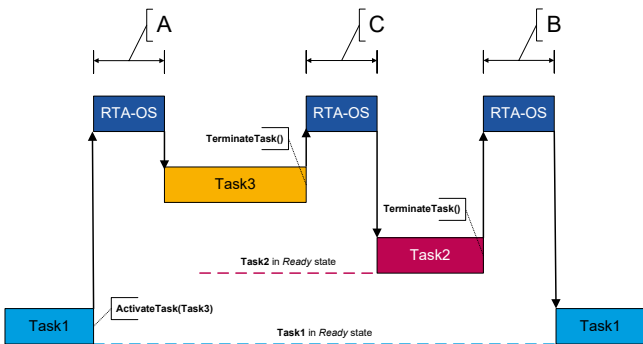


Figure 1 - Task1 is preempted by Task3, followed by a task switch and then normal termination of Task2

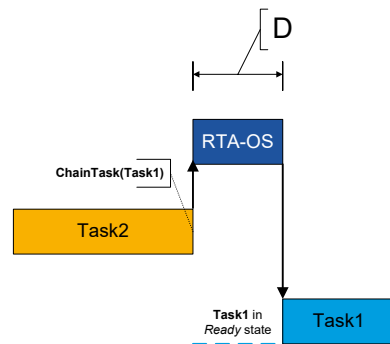


Figure 2 - Task2 chains Task1

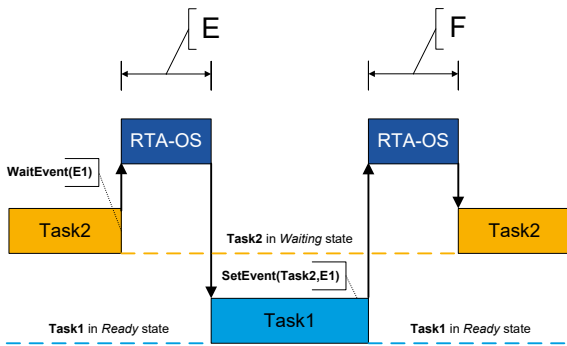


Figure 3 - Task2 waits for an event set by Task1

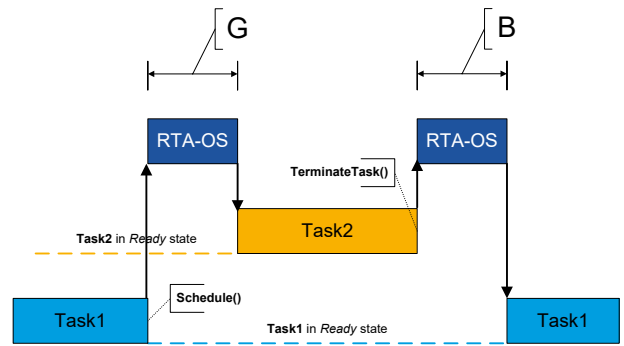


Figure 4 - Task1 allows cooperative scheduling by Task2

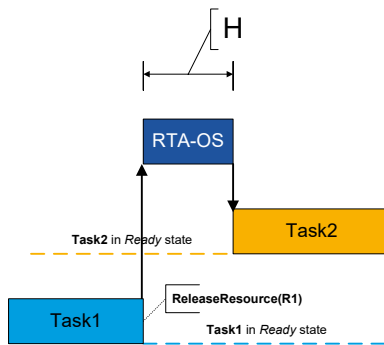


Figure 5 - Task1 releases a resource

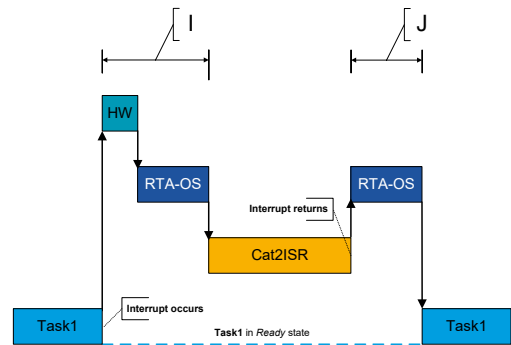


Figure 6 - Category2 ISR entry and exit latency

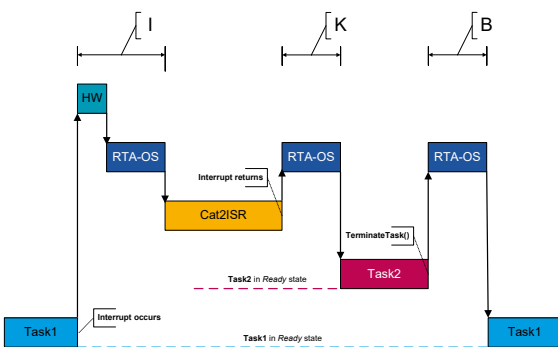


Figure 7 - Category2 ISR switches to Task2

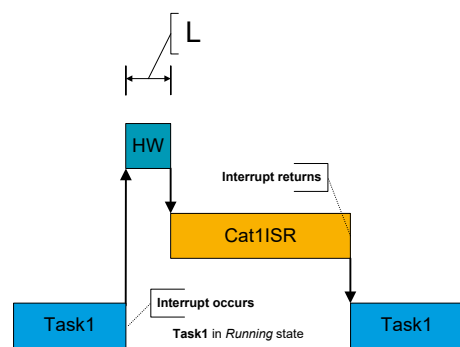


Figure 8 - Category1 ISR entry latency

## Order Information

To use RTA-OS it is necessary to purchase a development license for the tools together with an add-on license for the Cypress Traveo-II Green Hills port. Machine-named, user-named and floating licenses are available.

### RTA-OS Tools Order Information

Item	Characteristics	Object
F 00K 107 119	Machine-named license for RTA-OS for Windows PC	LD_RTA-OS_VRTA_SC34_LIC-MP
F 00K 107 120	User-named license for RTA-OS for Windows PC	LD_RTA-OS_VRTA_SC34_LIC-UP
F 00K 107 121	Floating license for RTA-OS for Windows PC	LD_RTA-OS_VRTA_SC34_LIC-CP
F 00K 107 136	Product CD for RTA-OS	LD_RTA-OS_VRTA_SC34_PROD

### RTA-OS Cypress Traveo-II Green Hills Port Order Information

Item	Characteristics	Object
F 00K 111 469	Machine-named license for RTA-OS for Cypress Traveo-II Green Hills Scalability Classes 1 & 2	ES_RTA-OS_TRAVEOIIIGHS_SC12_LIC-MP
F 00K 111 470	User-named license for RTA-OS for Cypress Traveo-II Green Hills Scalability Classes 1 & 2	ES_RTA-OS_TRAVEOIIIGHS_SC12_LIC-UP
F 00K 111 471	Floating license for RTA-OS for Cypress Traveo-II Green Hills Scalability Classes 1 & 2	ES_RTA-OS_TRAVEOIIIGHS_SC12_LIC-CP
F 00K 111 472	Machine-named license for RTA-OS for Cypress Traveo-II Green Hills Scalability Classes 1 to 4	ES_RTA-OS_TRAVEOIIIGHS_SC34_LIC-MP
F 00K 111 473	User-named license for RTA-OS for Cypress Traveo-II Green Hills Scalability Classes 1 to 4	ES_RTA-OS_TRAVEOIIIGHS_SC34_LIC-UP
F 00K 111 474	Floating license for RTA-OS for Cypress Traveo-II Green Hills Scalability Classes 1 to 4	ES_RTA-OS_TRAVEOIIIGHS_SC34_LIC-CP
F 00K 111 485	Product CD for RTA-OS for Cypress Traveo-II Green Hills	ES_RTA-OS_TRAVEOIIIGHS_PROD

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